# **Vibration Analyst Category III Equations**

#### **FORCES**

#### **Mass Unbalance**

$$F = Me \left(\frac{2\pi N}{60}\right)^2$$

M = W/g

W = weight of rotor or balance weight, lb

e = rotor eccentricity or radius of balance weight, in

 $g = gravitational constant, 386.1 in/s^2$ 

N = RPM

### **Spring Force**

F = Kx

K = stiffness of spring, lb/in

x = relative deflection, in

### **Damping Force**

 $F = C\dot{x}$ 

C = damping constant, lb-s/in

 $\dot{x}$  = relative velocity

#### **Inertia Force**

 $F = M \ddot{x}$ 

 $M = mass, lb-s^2/in$ 

 $\ddot{\mathbf{x}}$  = acceleration, in/s<sup>2</sup>

#### **MOTIONS**

### Velocity (in/s)

 $V = D(2\pi f)$ 

D = peak displacement, in

f = frequency, cycles/s (CPS)

 $\pi = 3.14$ 

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Vibration Analyst: Category III Equations Revision: 0 2011-09-15 English/EU Approved: D. Corelli

Page 1 of 3

#### **Acceleration**

$$A = V(2\pi f)$$

A = acceleration, 
$$in/s^2$$
  
1 g = 386.1  $in/s^2$ 

### **FREQUENCIES**

### **Bearing Frequencies**

$$\begin{aligned} &\mathsf{FTF} = \left(\frac{\Omega}{2}\right) \!\! \left[ 1 - \! \left(\frac{\mathsf{B}}{\mathsf{P}}\right) \!\! \cos \mathsf{CA} \right] \\ &\mathsf{BPFI} = \! \left(\frac{\mathsf{N}}{2}\right) \! \Omega \!\! \left[ 1 + \! \left(\frac{\mathsf{B}}{\mathsf{P}}\right) \!\! \cos \mathsf{CA} \right] \\ &\mathsf{BPFO} = \! \frac{\mathsf{N}}{2} \Omega \!\! \left[ 1 - \! \left(\frac{\mathsf{B}}{\mathsf{P}}\right) \!\! \cos \mathsf{CA} \right] \\ &\mathsf{BSF} = \! \left(\frac{\mathsf{P}}{2\mathsf{B}}\right) \! \Omega \!\! \left[ 1 - \! \left(\frac{\mathsf{B}}{\mathsf{P}}\right)^2 \cos^2 \mathsf{CA} \right] \end{aligned}$$

FTF = fundamental train frequency

BPFI = ball pass frequency, inner race

BPFO = ball pass frequency, outer race

BSF = ball spin frequency

CA = contact angle

 $\Omega$  = machine speed

N = number of rolling elements

P = pitch diameter, in

B = ball or roller diameter, in

### **Natural Frequency**

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

k = stiffness, lb/in

m = w/g

w = weight, lb

 $g = gravitational constant, 386.1 in/s^2$ 

 $f_n$  = natural frequency of a single-degree-of-freedom system, Hz

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Vibration Analyst: Category III Equations
Revision: 0 2011-09-15 English/EU
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Page 2 of 3

## **Roll Frequency**

$$f = \frac{V}{5\pi D}$$

V = web velocity, ft/min D = roll diameter, in f = frequency, Hz

### **SIGNAL PROCESSING**

### **Dynamic Range**

$$dB = 20 log \frac{V_m}{V_r}$$

$$\frac{V_m}{V_r} = 10^{\frac{dB}{20}}$$

 $V_{\rm m}$  = voltage measured  $V_{\rm r}$  = voltage reference

dB = decibels

#### **RMS**

peak = 1.414 rms

#### Resolution

Resolution = (frequency span x window noise factor x = 2)/#FFT lines

window noise factor =

- 1.0 for uniform window
- 1.5 for Hanning window
- 3.8 for flat top window

### **Data Acquisition Time (DAT)**

DAT = # FFT lines/frequency span

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Revision: 0 2011-09-15 English/EU Page 3 of 3